



IROMECE (Interactive Robotic Social Mediators as Companions)

Type of Project Intervention

Summary

IROMECE (Interactive Robotic Social Mediators as Companions) is a modular mobile robotic platform developed in a three year project which started in November 2006. It was cofunded by the European Commission within the RTD activities of the Strategic Objective SO 2.6.1 “Advanced Robotics” of the 6th Framework Programme (2006-2009). It was designed to become a social mediator for children with different levels of impairments such as cognitive disabilities, severe motor impairments and autism.

Low-tech, high-tech products, services and contexts for play

IROMECE is a mobile robotic platform designed to encourage disabled children to engage in social interaction via play scenarios. IROMECE is tailored towards children with autism, children with cognitive disabilities and children with motor impairments. The robot can engage in different play scenarios. The play scenarios were developed according to the needs of the target users group and according to the ICF-CY (International Classification of Functioning – version for Children and Youth) (Robins et al., 2010). The main components of IROMECE are a mobile platform, an application module, a number of additional components that modify the appearance and behaviour of the robot (Marti et al., 2010). Each element of the visual interface was designed using only a few variations and basic geometric shapes according to the needs of the impaired children, which are its main target user group (Lehmann et al. 2011). The robot is able to move in space autonomously and remotely controlled through a joy pad, or a button. IROMECE’s movements were designed not to be just functional in the interaction but also expressive in order to engage and sustain the children in the interaction. IROMECE is able to detect obstacles and persons in its surrounding through ultrasound and infrared sensors located on the mobile platform.

The context of use

It is possible to use IROMECE in different context such as education and rehabilitation centres.

Type of play in this play system

Cognitive

Practice
Symbolic
Constructive
Rule play (including videogames)

Social

Associative
Cooperative

Objectives related to play according to ICF-CY

Play for the sake of play: Major life areas - d880 engagement in play

d8802 parallel play
d8803 shared cooperative play
d8808 engagement in play, other specified
d8809 engagement in play, unspecified

Community social and civic life - d920 recreation and leisure time

d9200 play

Play-like activities: Therapeutic and educational objectives

b1 Mental functions
b2 Sensory functions and pain
d1 Learning and applying knowledge (learning through symbolic play, learning through pretend play)
d3 Communication
d4 Mobility
d7 Interpersonal interactions and relationships

Number of participants

10-20

Chronological Age

6-12 years

LUDI Categories of disabilities

Mental/intellectual impairments::
mild
moderate
Communication disorders (speech and language disorders):
Physical impairments:
Mild
Autism Spectrum Disorders:
Multiple disabilities:

Explanation on the use of low-tech, high-tech devices, services or contexts

Explanation

Verbal instruction, language and communication is adapted
Visual and/or verbal instruction with AAC (Aumentative and Alternative Communication)
Visual instruction with pictures or drawings
Prompting: therapist/researcher touches the participant as a key for further actions
Modeling by peer

Involvement

Adult: therapist/educator/researcher

Peer without disabilities

Role

Participatory observer
Providing instruction

Evaluation of objectives and outcome measures

Description of outcome measure(s)

Observation by professional/researcher providing the play experience
Video analysis
Feedback from client/parents/professionals
(validated and reliable) outcome measures like tests, self-reports of client/system, questionnaires

Information about availability of outcome measure: publisher, website, contact person

www.roboticsandlearning.org
Prof. Patrizia Marti, patrizia.marti@unisi.it
Iolanda Iacono PhD, iolanda.iacono@gmail.it

Summary of achieved effects

IROMEC robot seemed to have had a positive influence on the children's individual development.

IROMEC contributes to:

- help children to engage in play
- improve the social inclusion;
- facilitate the learning environment;
- facilitate the mediation child-human and child-child
- transfer some of the skills learned during the sessions with the robots

The use of IROMEC with children with ADHD and some traits of autism seems to be advantageous due to its mobile characteristics, which facilitate the needs of children with this specific disorder more explicitly.

References to the intervention or research project

Prof. Patrizia Marti, patrizia.marti@unisi.it
Iolanda Iacono, iolanda.iacono@unisi.it

Contact Person

Prof. Patrizia Marti, patrizia.marti@unisi.it
Iolanda Iacono, iolanda.iacono@unisi.it

Website

www.roboticsandlearning.org

Publication

-Marti, P. Materials of Embodied Interaction. Proceedings of 14th ACM International Conference on Multimodal Interaction, ICMI 2012, Santa Monica, California. October 22-26th, 2012.

-Iacono, I. Lehmann, H. Marti, P. Robins, B. Dautenhahn, K. Robots as Social Mediators for Children with Autism – A Preliminary Analysis Comparing Two Different Robotic Platforms. Proceedings of the First International Conference on Development and Learning (ICDL) and the International Conference on Epigenetic Robotics (EpiRob), Frankfurt, Germany, 24-27 August 2011.

-Lehmann, H. Iacono, I. Robins, B. Marti, P. Dautenhahn, K. „Make it move“: Playing cause and effect games with a robot companion for children with cognitive disabilities. Proceedings of the 29th annual conference of the European Association of Cognitive Ergonomics, ECCE 2011, “Designing Collaborative Activities, August 24th – 26th, 2011; Rostock, Germany.

-Marti, P. Iacono, I. Learning Through Play With a Robot Companion. Proceedings of the 11th European Conference for the Advancement of Assistive Technology, AAATE 2011, August 31 – September 2, 2011, Maastricht, the Netherlands.

-Marti, P. Perceiving while being perceived. International Journal of Design, 4(2), 2010.

-Marti, P. “Bringing playfulness to disability” Proceedings of the 6th Nordic Conference on Human-Computer Interaction, NordiCHI 2010, Reykjavik, Iceland, 17-20 October 2010.

-Marti, P. Iacono, I. Oliverio, M. Il Robot Come Compagno Di Gioco Nella Disabilità Infantile. Atti del IX Congresso Nazionale della Società Italiana di Ergonomia, “Ergonomia, Valore sociale e sostenibilità, Roma, 27-29 Ottobre 2010.

-Marti P., Giusti L. A Robot Companion for Inclusive Games: a user-centred design perspective. In: Proceedings of the IEEE International Conference on Robotics and Automation. Anchorage, Alaska, USA, 3-8 May 2010.

-Robins, B. Ferrari, E. Dautenhahn, K. Kronrief, G. Prazak, B. Gerderblom, G.J. Bernd, T. Caprino, F. Laudanna, E. Marti, P. Human-centred Design Methods: Developing Scenarios for Robot Assisted Play Informed by User Panels and Field Trials. International Journal of Human Computer Studies, 2010, Volume 68 Issue 12, 873-898, December, 2010, ISSN: 1071-5819. DOI

-Marti, P. Giusti, L. Pollini, A. Exploring play styles with a robot companion. Proceedings of IEEE RO-MAN 2009, 18th IEEE International Symposium on Robot and Human Interactive Communication, 27 September – 2 October 2009, Toyama, Japan.

-Marti, P., Giusti, A., Rullo, A. Robots as social Mediators: field trials with children with special needs. Proceedings of the AAATE Conference, Firenze, 31 Agosto – 2 Settembre. In: Emiliani, P.L., Burzagli, L., Como, A., Gabbanini, F., Salminen, A.L. (Eds) Adaptive Technology from adapted equipment to inclusive environments, Amsterdam, Olanda: IOS Press, 165-169, 2009.

-Marti, P., Giusti, L., Pollini, A., Rullo, A. (2009) Expressiveness in human-robot interaction. IxD&A – Interaction Design & Architecture(s), “Design for the Future Experience” N. 5&6, 2009, pp93-98, ISSN 1826-9745, ISBN 978-88-88044-14-9 pp. 23 – 30. Special issue: Computer Human Interaction Italy 2009 – CHIItaly’09 (Roma, 17-19 June 2009). ACM SIGCHI Italy (ed.). IxD&A, 2009.

-Marti, P. Moderini, C. Giusti, L. Pollini, A. A Robotic Toy for Children with special needs: From requirements to Design. Proceedings of ICORR09, The 11th IEEE International Conference in Rehabilitation Robotics “Reaching Users & the Community” 23-26 June 2009 Kyoto, Japan.

-Marti, P. Critical Factors related to Design and Development. In S. Besio (ed.) Analysis of Critical Factors involved in using interactive robots for education and therapy of children with disabilities, UNIService Trento, 2009. ISBN 978-886178-401-7.

Keywords

IROME C
Children
Autism
Cognitive Disabilities
Motor Disabilities
Play
Human-Robot Interaction